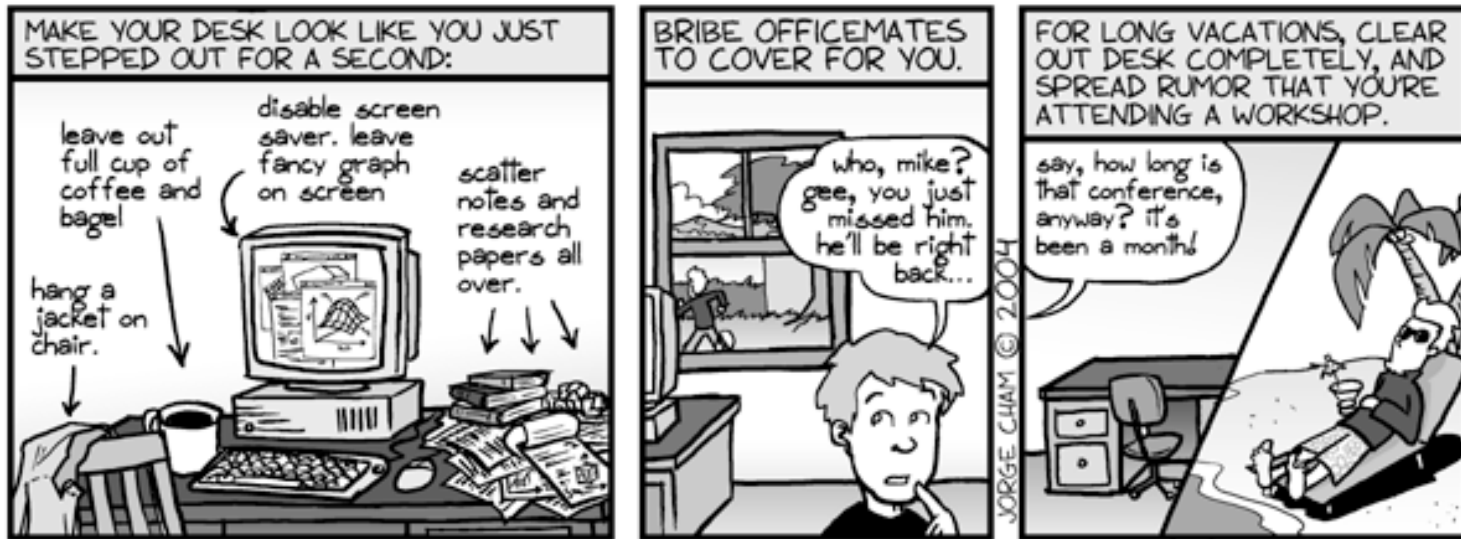


14 - final project - manuscript review

HOW TO LOOK BUSY EVEN IF YOU'RE NOT PART 2: LOOKING BUSY IN YOUR ABSENCE



ME338A - Final project - Paper review - due in class Thu, March 11, 2010, 11am

Constitutive modelling of passive myocardium

A structurally-based framework for material characterization

Gerhard A. Holzapfel & Ray W. Ogden

Philosophical Transactions of the Royal Society A 2009,367:3445-3475.

This final project will demonstrate that during the past 10 weeks, you have learned to read state of the art continuum mechanics literature. Gerhard Holzapfel and Ray Ogden, two leading scientists in continuum biomechanics, have recently published a manuscript that introduces a new continuum mechanics model for passive cardiac muscle tissue.

- 1 Read the publication and try to understand what it is all about. You do not necessarily need to understand **all** the equations. You can briefly glance over section 6, it is not relevant for this final project.
- 2 Summarize the manuscript in less than 200 words.
- 3 Ogden & Holzapfel use a slightly different notation than we have used in class, i.e., they do not use dots to indicate scalar products. Rewrite equations (3.1) to (3.14) in our tensor notation, i.e., use the dot for scalar products when appropriate.
- 4 Rewrite equations (3.1) to (3.14) in index notation. For each equation, state in brackets whether it is a scalar, vectorial, or second order tensorial equation.
- 5 In section 4, Ogden & Holzapfel review existing constitutive models for passive cardiac tissue. They discuss three transversely isotropic models (4.1), (4.2), and (4.3) and three orthotropic models (4.5), (4.7), and (4.8). Summarize these six models in a table. For each model, list the first author, the year it was published, the invariants it is based on, and the parameters that are needed.

- 6 Figure 4 illustrates the deformation state of simple shear. Calculate the Green Lagrange strain tensor $E = \frac{1}{2} [F^t \cdot F - I]$ from the deformation gradient given in (5.9) and sketch the deformed configuration in the fs -plane.
- 7 Equation (5.38) is the key equation of the paper. It introduces the free energy function for myocardial tissue. Describe its three terms and explain the required material parameters.
- 8 Most soft biological tissues are incompressible and anisotropic. How are incompressibility and anisotropy handled in this constitutive formulation?
- 9 Review the publication with the help of the attached spreadsheet. Use common sense to answer the questions you cannot answer based on your current continuum mechanics knowledge. There are no wrong answers, and we will not take off points as long as you can justify your opinion.

Instructions

Please rate this manuscript on a scale of 1-5, with 1 indicating greatest degree or best, and 5 indicating least degree or poor. You must also provide comments to the authors in prose. It is not acceptable to merely fill out numbers, and return the review.

Manuscript title _____

Authors _____

Summary (required brief summary of the context)

Presentation	(best)	1	2	3	4	5	(poor)
is clearly written		<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	
title is appropriate		<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	
abstract is appropriate		<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	
figures and tables are adequate		<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	
problem statement is clear		<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	
provides appropriate detail		<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	
describes limitations		<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	
references are adequate		<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	

Comments (required in addition to the number ratings above)

Significance	(best)	1	2	3	4	5	(poor)
represents important advance		<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	
addresses important and realistic problem		<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	
is likely to scale up to realistic problems		<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	
provides new evidence for existing technique		<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	

Comments (required in addition to the number ratings above)

Originality	(best)	1	2	3	4	5	(poor)
novel approach or combination of approaches		<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	
has not been published before		<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	
points out differences from related research		<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	
reformulates a problem in an important way		<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	

Comments (required in addition to the number ratings above)

Technical content	(best)	1	2	3	4	5	(poor)
evaluates effectiveness of techniques		<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	
is supported with sound arguments		<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	
is supported with theoretical analysis		<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	
is supported with experimental results		<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	
is technically sound		<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	

Additional comments to the authors

Overall recommendation accept marginal reject

Your confidence in recommendation strong medium weak

Confidential comments to the editor

Confidential reviewer name _____

Constitutive modelling of passive myocardium: a structurally based framework for material characterization

BY GERHARD A. HOLZAPFEL^{1,2,*} AND RAY W. OGDEN³

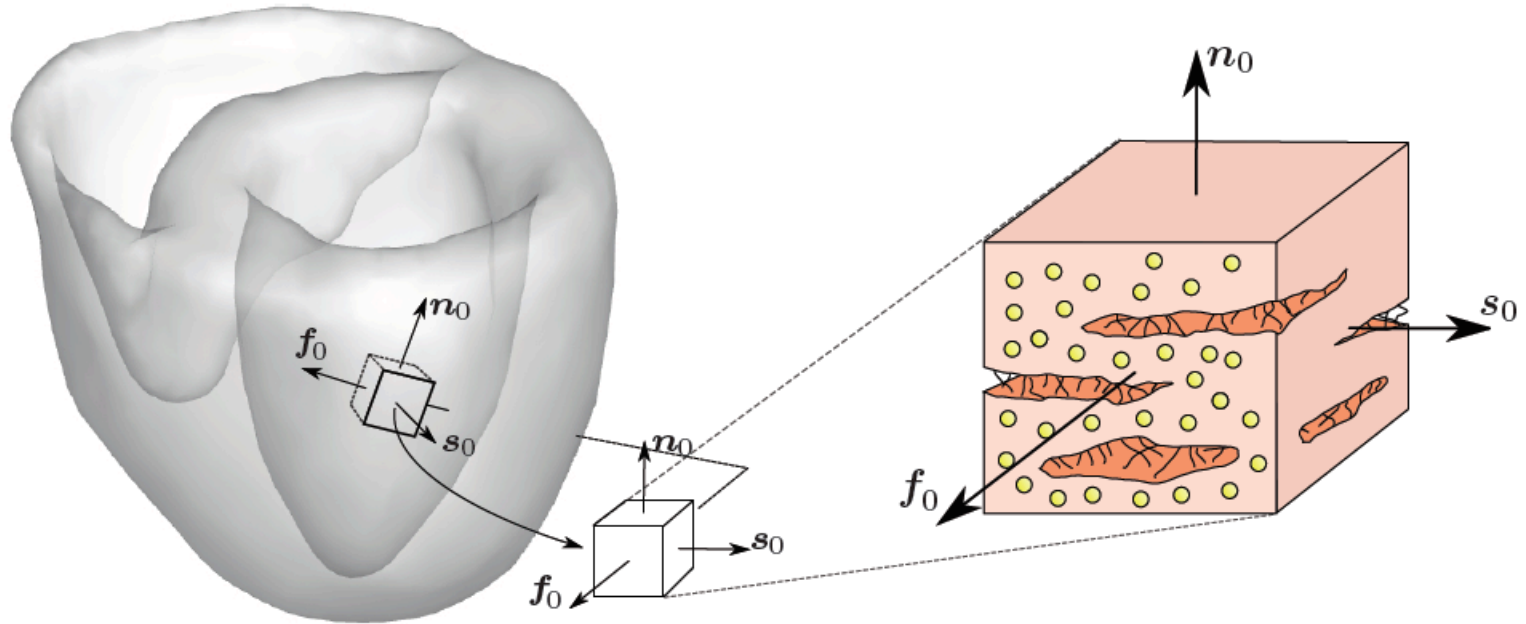
¹*Department of Solid Mechanics, School of Engineering Sciences, Royal Institute of Technology (KTH), Osquars Backe 1, 100 44 Stockholm, Sweden*

²*Institute of Biomechanics, Center of Biomedical Engineering, Graz University of Technology, Kronesgasse 5-I, 8010 Graz, Austria*

³*Department of Mathematics, University of Glasgow, University Gardens, Glasgow G12 8QW, UK*

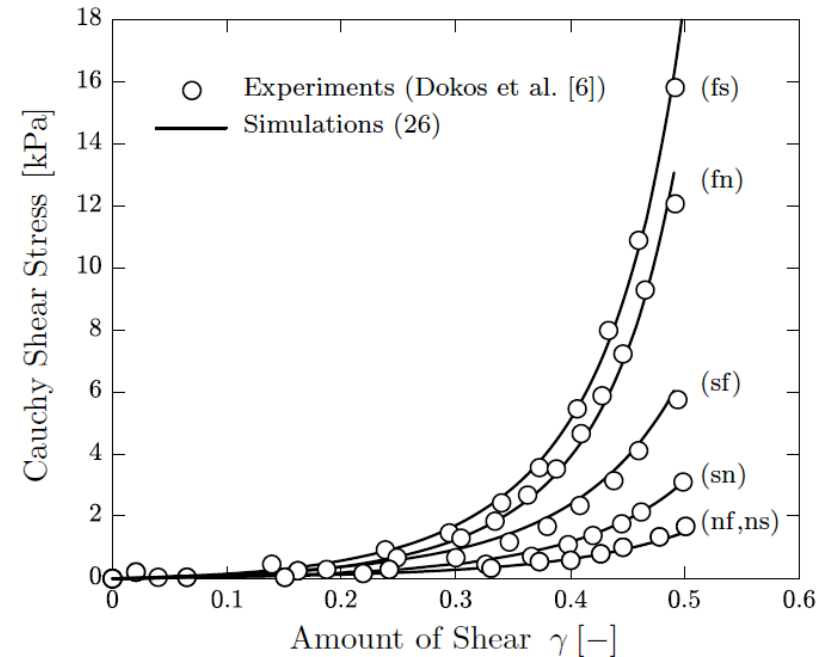
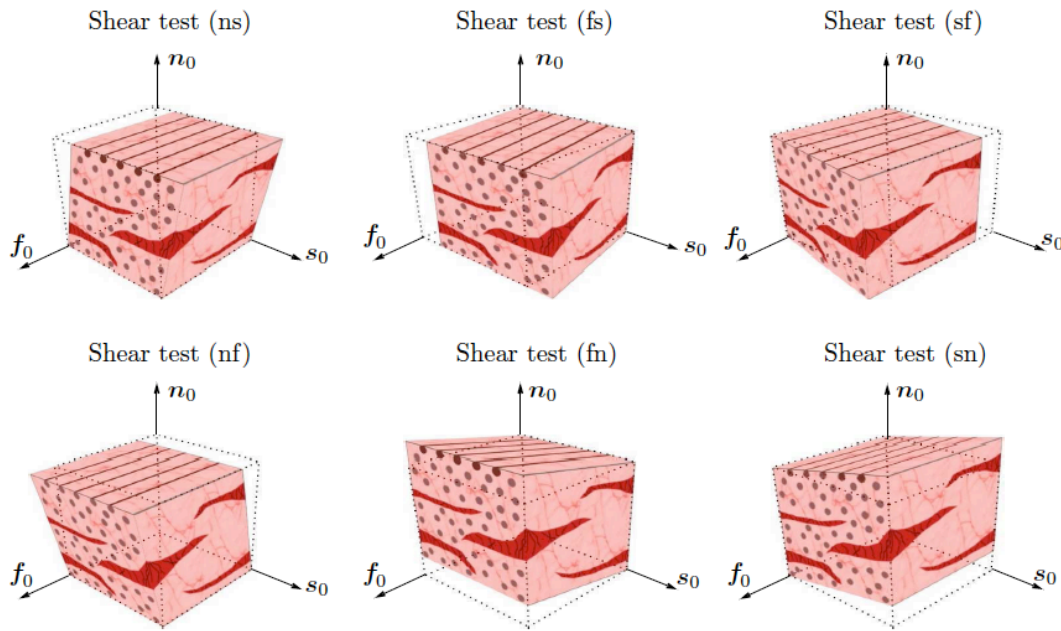
passive - *in vitro* measurement vs *in silico* prediction

$$\bar{\Psi}(\mathbf{g}; \bar{\mathbf{F}}, \mathbf{M}, \mathbf{S}) = \frac{a}{2b} \exp[b(\bar{I}_1 - 3)] + \sum_{i=f,s} \frac{a_i}{2b_i} \{ \exp[b_i(\bar{I}_{4i} - 1)^2] - 1 \} + \frac{a_{fs}}{2b_{fs}} [\exp(b_{fs}\bar{I}_{8fs}^2) - 1]$$



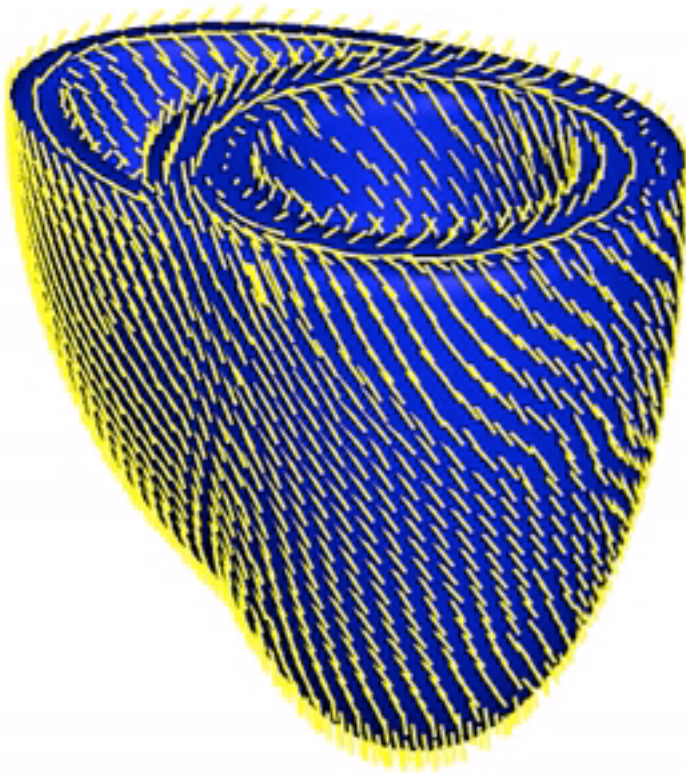
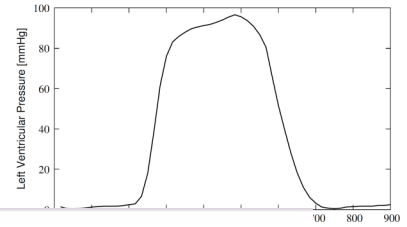
dokos, smail, young, le greece [2002], holzapfel, ogden [2009], göktepe, acharya, wong, kuhl [2009]

passive - *in vitro* measurement vs *in silico* prediction



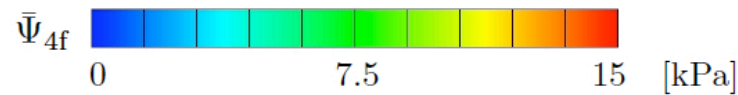
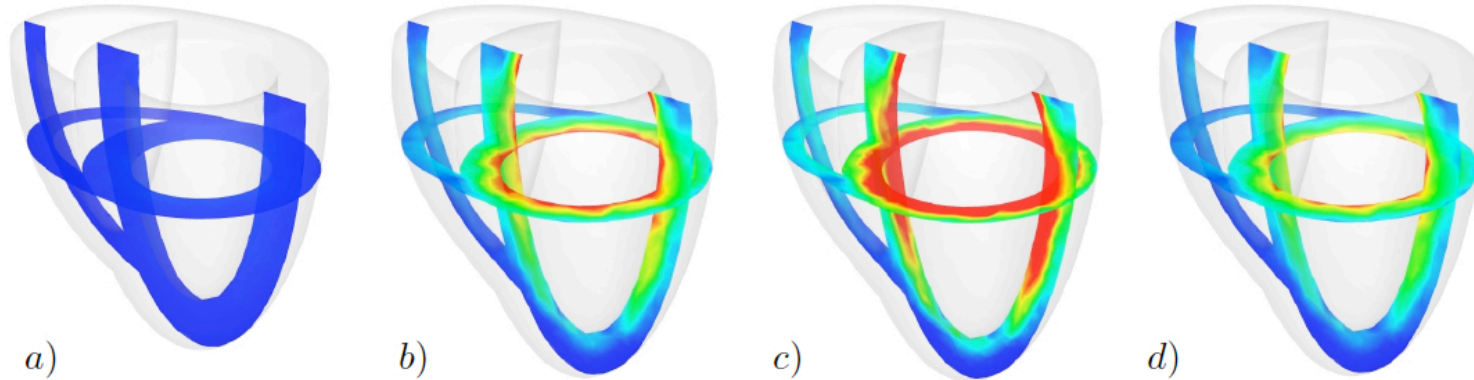
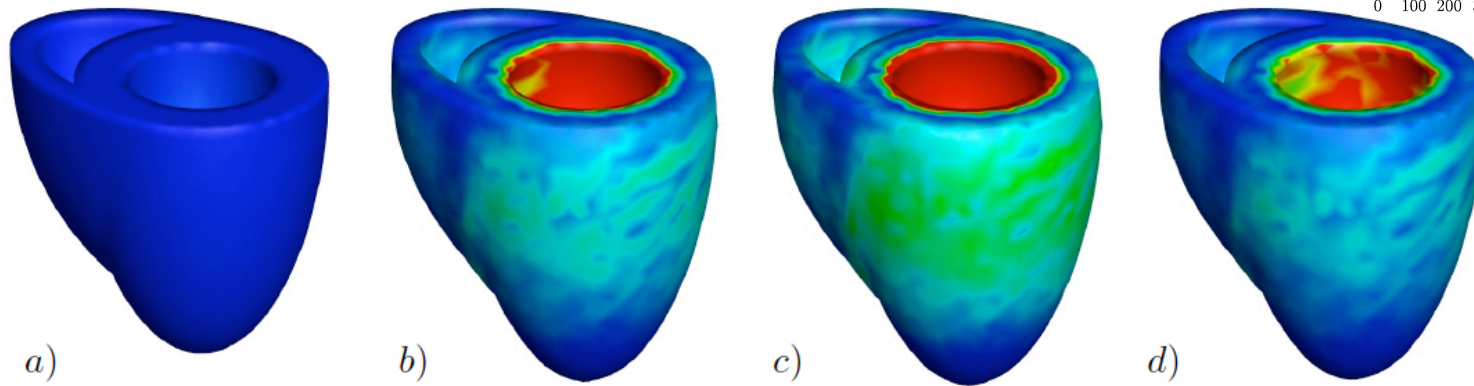
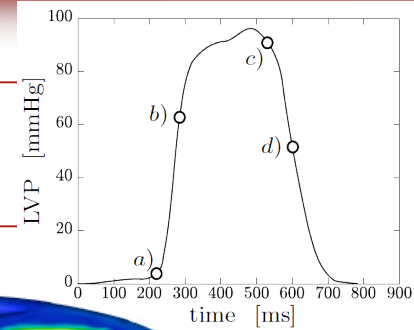
dokos, smail, young, le greece [2002], holzapfel, ogden [2009], göktepe, acharya, wong, kuhl [2009]

passive response - *in silico* prediction



göktepe, acharya, wong & kuhl [2009]

passive response - *in silico* prediction

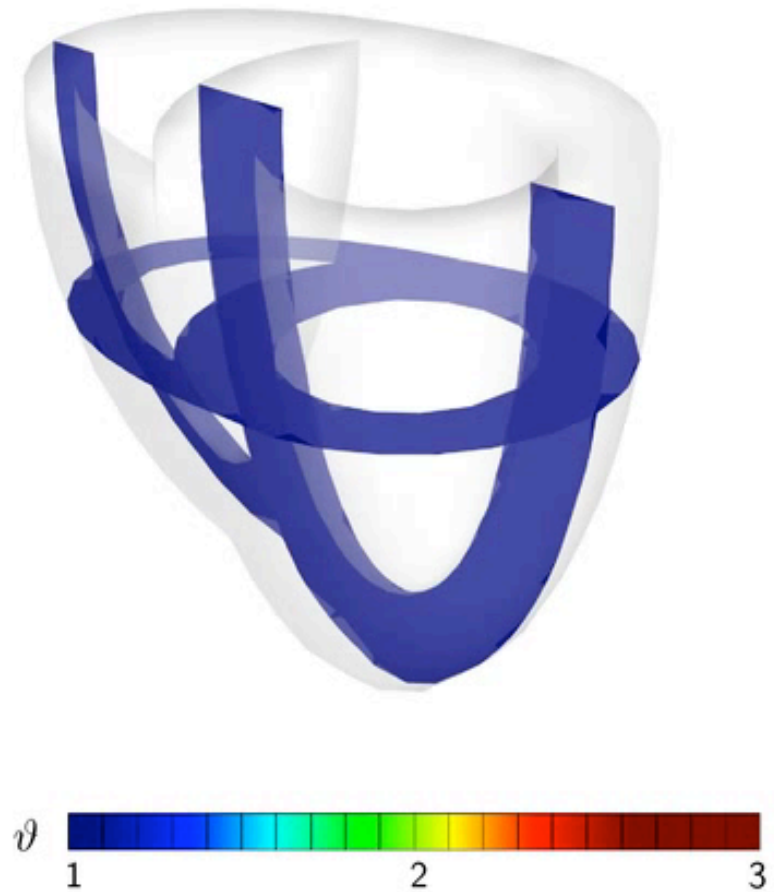
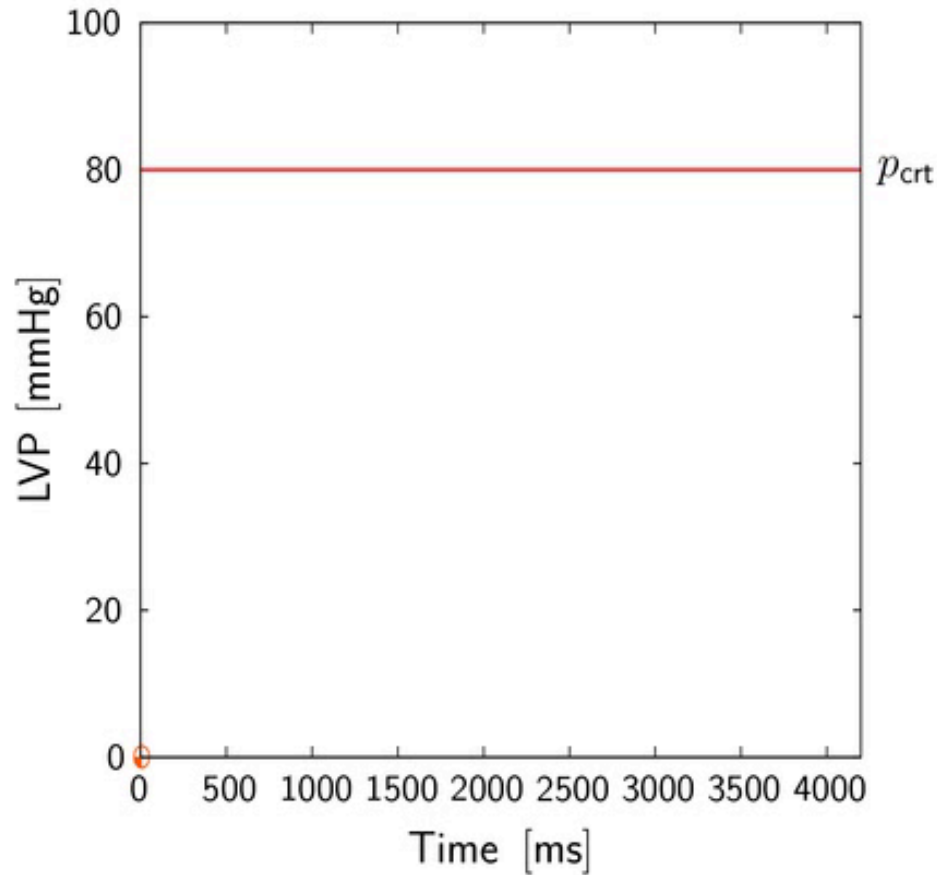


göktepe, acharya, wong, kuhl [2009]



intro to the heart - tue 03/09/10

hypertrophic wall thickening



current research in our group

linear hyperelasticity

$$\mathbb{I}\mathbb{E} = \lambda \mathbf{I} \otimes \mathbf{I} + 2\mu \mathbb{I}\mathbb{I}^{\text{sym}} \quad \boldsymbol{\sigma} = \mathbb{I}\mathbb{E} : \boldsymbol{\epsilon}$$

$$\mathbb{I}\mathbb{E} = \begin{bmatrix} \lambda + 2\mu & \lambda & \lambda & 0 & 0 & 0 \\ \lambda & \lambda + 2\mu & \lambda & 0 & 0 & 0 \\ \lambda & \lambda & \lambda + 2\mu & 0 & 0 & 0 \\ 0 & 0 & 0 & \mu & 0 & 0 \\ 0 & 0 & 0 & 0 & \mu & 0 \\ 0 & 0 & 0 & 0 & 0 & \mu \end{bmatrix}$$

two Lamé parameters λ and μ .

volumetric deviatoric decomposition

$$\mathbb{I}\mathbb{E} = 3 \kappa \mathbb{I}\mathbb{I}^{\text{vol}} + 2 \mu \mathbb{I}\mathbb{I}^{\text{dev}} \quad \sigma = \mathbb{I}\mathbb{E} : \epsilon$$

$$\mathbb{I}\mathbb{E} = \begin{bmatrix} \kappa + \frac{4}{3}\mu & \kappa - \frac{2}{3}\mu & \kappa - \frac{2}{3}\mu & 0 & 0 & 0 \\ \kappa - \frac{2}{3}\mu & \kappa + \frac{4}{3}\mu & \kappa - \frac{2}{3}\mu & 0 & 0 & 0 \\ \kappa - \frac{2}{3}\mu & \kappa - \frac{2}{3}\mu & \kappa + \frac{4}{3}\mu & 0 & 0 & 0 \\ 0 & 0 & 0 & \mu & 0 & 0 \\ 0 & 0 & 0 & 0 & \mu & 0 \\ 0 & 0 & 0 & 0 & 0 & \mu \end{bmatrix}$$

two parameters $\kappa = \lambda + \frac{2}{3}\mu$ and μ .

4.3 linear hyperelasticity

relations between elastic constants

	E, ν	E, μ	λ, μ	κ, μ
E	E	E	$\frac{\mu [3\lambda + 2\mu]}{\lambda + \mu}$	$\frac{9\kappa\mu}{3\kappa + \mu}$
ν	ν	$\frac{E - 2\mu}{2\mu}$	$\frac{\lambda}{2[\lambda + \mu]}$	$\frac{3\kappa - 2\mu}{6\kappa + 2\mu}$
μ	$\frac{E}{2[1 + \nu]}$	μ	μ	μ
λ	$\frac{E\nu}{[1 + \nu][1 - 2\nu]}$	$\frac{\mu[E - 2\mu]}{3\mu - E}$	λ	$\kappa - \frac{2}{3}\mu$
κ	$\frac{E}{3[1 - 2\nu]}$	$\frac{E\mu}{3[3\mu - E]}$	$\lambda + \frac{2}{3}\mu$	κ



4.3 linear hyperelasticity

transversely isotropic hyperelasticity

a **transversely isotropic material** is symmetric about an axis that is normal to a plane of isotropy. within this plane, the material properties are the same in all directions. the number of independent constants in the elasticity tensor reduces from 21 to five:

$C_{11}, C_{33}, C_{12}, C_{13}, C_{44}$, here $\mathbf{n} = [0, 0, 1]^t$

$$\begin{pmatrix} C_{11} & C_{12} & C_{13} & 0 & 0 & 0 \\ & C_{11} & C_{13} & 0 & 0 & 0 \\ & & C_{33} & 0 & 0 & 0 \\ & & & C_{44} & 0 & 0 \\ & \text{symmetric} & & & C_{44} & 0 \\ & & & & & (C_{11} - C_{12})/2 \end{pmatrix}$$



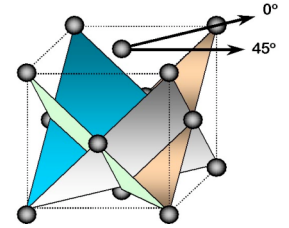
orthotropic hyperelasticity

an **orthotropic material** is symmetric about two or three mutually orthogonal two-fold axes of rotational symmetry. its material properties are in general different along each axis. the number of independent constants reduces from 21 to nine: $C_{11}, C_{22}, C_{33}, C_{12}, C_{23}, C_{31}, C_{44}, C_{55}, C_{66}$

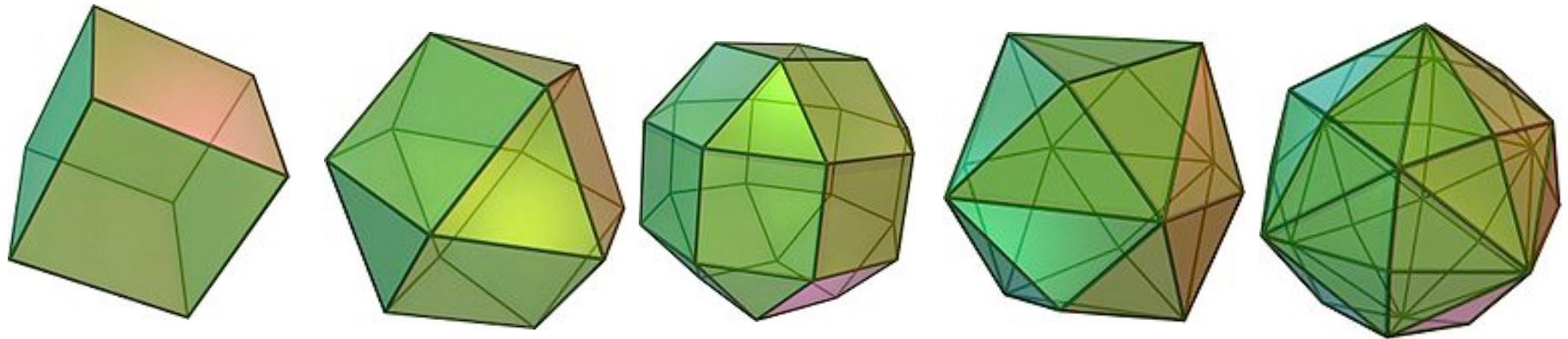
$$\begin{bmatrix} C_{11} & C_{12} & C_{13} & 0 & 0 & 0 \\ C_{12} & C_{22} & C_{23} & 0 & 0 & 0 \\ C_{13} & C_{23} & C_{33} & 0 & 0 & 0 \\ 0 & 0 & 0 & C_{44} & 0 & 0 \\ 0 & 0 & 0 & 0 & C_{55} & 0 \\ 0 & 0 & 0 & 0 & 0 & C_{66} \end{bmatrix}$$



symmetry groups



the **symmetry group** of an object is the group of all isometries under which it is invariant with composition as the operation. it is a subgroup of the isometry group of the space concerned. a typical example are the symmetric lattices of fcc and bcc crystals.



example: double cork 1080

spins are referred to as **corked** or corkscrew when the axis of the spin allows for the snowboarder to be temporarily oriented sideways in the air, typically without becoming completely inverted. a **double-cork** refers to a rotation in which a snowboarder inverts or orients himself sideways **at two distinct times** during an aerial rotation.





double mctwist 1260

the **mctwist** was invented in the early 1980s by skateboarder mike mcgill, and has since been adopted by snowboarders. to perform the trick, the rider does a front flip while at the same time spinning a backside 540. a variety of grabs are used to give the trick more style. in early 2010, shaun white debuted a new trick - the **double mctwist 1260**, which involves **two flips and three and a half spins**.



